

Data sheet for three-phase Squirrel-Cage-Motors INNOMOTICS



Motor type : 1AV3083A

INNOMOTICS GP - 80 M - IM B3 - 2p

Client order no.	Item-No.	Offer no.
Order no.	Consignment no.	Project

Remarks

Safe Area

Electrical data

-/-

U [V]	Δ / Y	f [Hz]	P [kW]	P [hp]	I [A]	n [1/min]	M [Nm]	η ³⁾			$\cos\phi$ ³⁾			I_A/I_N I_I/I_N	M_A/M_N T_I/T_N	M_K/M_N T_B/T_N	IE-CL
								4/4	3/4	2/4	4/4	3/4	2/4				
DOL duty (S1) - 155(F) to 130(B)																	
230	Δ	50	1.10	-/-	3.95	2885	3.6	82.7	83.9	83.1	0.85	0.80	0.69	7.1	3.0	3.3	IE3
400	Y	50	1.10	-/-	2.25	2885	3.6	82.7	83.9	83.1	0.85	0.80	0.69	7.1	3.0	3.3	IE3
460	Y	60	1.27	-/-	2.25	3480	3.5	84.0	84.6	83.4	0.85	0.80	0.71	7.4	2.8	3.4	IE3
460	Y	60	1.10	-/-	1.98	3500	3.0	84.0	84.0	82.0	0.83	0.77	0.67	8.4	3.3	4.0	IE3
IM B3 / IM 1001		FS 80 M		IP55		UKCA		IEC/EN 60034		IEC, DIN, ISO, VDE, EN							
Environmental conditions : -20 °C - +40 °C / 1000 m										Locked rotor time (hot / cold) : 14.4 s 19.5 s							

Mechanical data

Sound level (SPL / SWL) at 50Hz 60Hz	60 / 71 dB(A) ^{2) 3)}	64 / 75 dB(A) ^{2) 3)}	Vibration severity grade	A
Moment of inertia	0.0013 kg m ²		Thermal class	F
Bearing DE NDE	6004 2Z C3	6004 2Z C3	Duty type	S1
bearing lifetime			Direction of rotation	bidirectional
L_{10mh} $F_{Rad, min}$ for coupling operation 50 60Hz ¹⁾	40000 h	32000 h	Frame material	aluminum
Regreasing device	Without		Net weight of the motor (IM B3)	12 kg
Grease nipple	-/-		Coating (paint finish)	Standard paint finish C2
Type of bearing	Preloaded bearing DE		Color, paint shade	RAL7030
Condensate drainage holes	Without		Motor protection	(A) without (Standard)
External earthing terminal	Without		Method of cooling	IC411 - self ventilated, surface cooled

Terminal box

Terminal box position	top	Max. cross-sectional area	1.5 mm ²
Material of terminal box	Aluminium	Cable diameter from ... to ...	9 mm - 17 mm
Type of terminal box	TB1 E00	Cable entry	1xM25x1,5
Contact screw thread	M4	Cable gland	1 plug

I_A/I_N = locked rotor current / current nominal
 M_A/M_N = locked rotor torque / torque nominal
 M_K/M_N = break down torque / nominal torque

1) L_{10mh} according to DIN ISO 281 10/2010
 2) at rated power / at full load
 3) Value is valid only for DOL operation with motor design IC411

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